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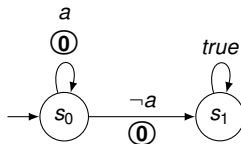
Execution and monitoring of HOA automata with HOAX

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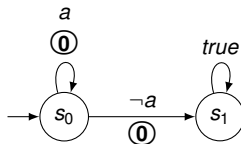
TU Wien, Austria

RV, September 16, 2025

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HOA: v1
States: 2
Start: 0
AP: 1 "a"
Acceptance: 1 Inf(0)
Alias: @a 0
--BODY--
State: 0 "s0"
[@a] 0 {0}
[!@a] 1 {0}
State: 1 "s1"
[t] 1
--END--
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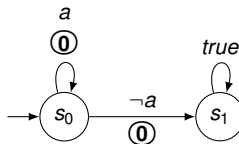


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Tools: Owl, Spin, Spot, Prism, SemML, Strix, AutoHyper ...

Owl

A command-line tool and a library for **Omega-words**, ω -automata and Linear Temporal Logic (LTL).



Competitions: SYNTCOMP

- **Execute** automaton based on the semantics of HOA

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- **Configurable** input sources for automata inputs (**drivers**)
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 - File-based
- Provide **scriptable** condition-reaction mechanisms (**hooks**)
 - **If** (state reached / trace longer than x / etc.) ...
 - ... **Then** (reset automaton / print message / etc.)

Command line

```
$ hoax aut.hoa --config conf.toml
```

```
1  _____ conf.toml _____  
2  # Main section (mandatory)  
3  [hoax]  
4  name = "My HOAX config" # Name for the configuration  
5  version = 1             # Config file version (mandatory)  
6  
7  # Driver for propositions that have none defined  
8  default-driver = "user" # User prompt (the default)  
9  
10 [[driver.flip]] # Notice the double brackets  
11 aps = ["a"]     # APs driven by this driver  
12 bias = 0.7       # Bias of "true" (optional, default=0.5)  
13  
14 [[driver.flip]]  
15 # (multiple "flip" drivers may be defined)  
16 aps = ["b", "c"]
```


Hook API example (Python)

- **Runner** objects track execution of an automaton
- We create **Hook** objects and append them to **Runners**

hook_example.py

```
1  # Instantiate runner
2  aut = ...                # HOA automaton (eg., parsed from file)
3  conf = DefaultConfig()   # or: conf = TomlConfigV1("config.toml")
4  run = SingleRunner(aut, conf.driver)
5
6  # Instantiate and add hook
7  condition = Reach(2)     # If state with index=2 is reached...
8  action = Reset()        # Then reset automaton to initial state
9  run.add_transition_hook(Hook(condition, action))
10
11 # Basic run loop
12 run.init()
13 try:
14     while True:
15         run.step()
16 except StopRunner:
17     pass
```

Just a natural **application** of the tool features

We built **Condition** classes that turn **true** iff the run so far is enough to establish that the run will be **accepted**

Then we merely add them to the runner via hooks

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$ hoax aut.hoa --config conf.toml --monitor
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```

Clearly only **some** acceptance conditions are actually monitorable. **Best effort** in general case

S = non-empty subset of states (or transitions)

$$\text{acc} ::= \text{Inf}(S) \mid \text{Fin}(S) \mid \text{acc} \wedge \text{acc} \mid \text{acc} \vee \text{acc}$$

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$\text{Inf}(S)$ Visit at least one element of S infinitely often

$\text{Fin}(S)$ Do not visit any element of S infinitely often

A trap set T of automaton \mathcal{A} is a non-empty subset of its states st. once a run enters T , it may **never leave**

- Trap sets may be nested
- **Minimal** trap sets have no nested trap sets
- They correspond to **bottom SCCs** of \mathcal{A}

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We can build a mapping MINTRAPSETOF from each state of \mathcal{A} to the **smallest** trap set that contains it

- Reduction from SCC/condensation graph of \mathcal{A}
- Indeed, it will return a **set of SCCs**
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Monitoring by comparing current trap to **acceptance set**

Example: checking for $\text{Inf}(S)$

Execute this algorithm after every step:

Input : Det. complete automaton \mathcal{A} ; its current state $q \in Q$

Output: good, bad, ugly, or \perp .

```
1  $Comps \leftarrow \text{MINTRAPSETOF}(q)$  #  $O(|Q|)$ 
2  $T \leftarrow \bigcup Comps$  #  $O(|Q|)$ 
3 if  $T \subseteq S$  then return good #  $O(|S|)$ 
4 if  $T \cap S = \emptyset$  then return bad #  $O(|S|)$ 
5 if  $T$  is minimal then
6   if  $T \setminus S$  is transient then return good else return ugly
   #  $O(|S| + |E_S|)$  (sub-graph limited to  $S$ )
7 return  $\perp$  # No verdict in this step
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- Good prefix \Leftrightarrow the run will be accepted
- Bad prefix \Leftrightarrow the run will be rejected
- X transient \Leftrightarrow every run of \mathcal{A} leaves X infinitely often
- Ugly prefix \Leftrightarrow further monitoring is hopeless

- Configurable tool to execute HOA automata
- Scriptable behaviour through Hooks API
- (Best-effort) monitoring of **any acceptance condition**

Future work:

- Performance improvements
 - Possibly enabled by Python/cPython evolution
- **DSL** to script hooks within configuration
- Go **beyond Booleans?**

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Try HOAX today!

```
$ pipx install hoax  
$ uv tool install hoax
```



<https://github.com/lou1306/hoax>